## Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application.

## **List of Claims**:

- (Original) A backlash reduction apparatus comprising:
   means for advancing a substrate;
   means for stopping advance of the substrate short of a final intended position; and
   means for finally advancing the substrate.
- 2. (Original) The apparatus of claim 1 wherein the means for stopping operates in response to a means for sensing substrate position.
- 3. (Original) The apparatus of claim 1 wherein the means for finally advancing comprises means for incrementally advancing the substrate.
- 4. (Original) The apparatus of claim 3 wherein the means for incrementally advancing comprises a position-controlled servo motor.
- 5. (Original) The apparatus of claim 3 wherein the means for incrementally advancing comprises a stepper motor.
- 6. (Original) The method of claim 5 wherein the means for finally advancing operates the stepper motor in full steps.
- 7. (Original) The method of claim 5 wherein the means for finally advancing operates the stepper motor in fractions of steps.
- 8. (Original) The method of claim 5 wherein the means for finally advancing operates the stepper motor in microsteps.

- 9. (Original) A backlash reduction apparatus comprising:
- a drive motor that can rotate in increments;
- a drive train driven by the drive motor;
- at least one substrate transport mechanism connected to the drive train and driven by the drive motor therethrough;
- a controller comprising:
- a substrate advancer in communication with the drive motor, the substrate advancer emitting control signals to the drive motor that cause the substrate to move to a point short of an intended destination; and
- a substrate final advancer in communication with the drive motor, the substrate final advancer sending control signals to the drive motor that cause the substrate to continue to the intended destination.
- 10. (Original) The apparatus of claim 9 wherein the drive motor is a position-controlled servo motor.
  - 11. (Original) The apparatus of claim 9 wherein the drive motor is a stepper motor.
- 12. (Original) The apparatus of claim 9 wherein the signals from substrate advancer cause the drive motor to stop the substrate a predetermined number of increments from the intended destination.
- 13. (Original) The apparatus of claim 12 wherein the predetermined number of increments is greater than a number of increments representing a total possible backlash error in the drive train.
- 14. (Original) The apparatus of claim 12 wherein the substrate final advancer signals cause the drive motor to advance by the predetermined number of increments.

- 15. (Original) The apparatus of claim 9 wherein the substrate final advancer stops the drive motor when a position sensor detects that the substrate has arrived at the intended destination.
  - 16. (Original) A backlash reduction method comprising:
    advancing a substrate to a point short of a final intended position;
    finally advancing the substrate to the final intended position, thereby taking up backlash in a substrate transport system.
- 17. (Original) The method of claim 16 further comprising monitoring substrate position and sending substrate position information to a controller that initiates the advancing and final advancing of the substrate.
- 18. (Original) The method of claim 16 wherein finally advancing includes advancing the substrate at a lower speed than the speed at which the substrate was advanced to the point short of the final intended destination.
- 19. (Original) The method of claim 16 wherein finally advancing includes advancing the substrate incrementally from the point short of the final intended destination to the final intended destination.
- 20. (Original) The method of claim 16 further comprising providing a drive motor, providing a substrate transport driven by the drive motor, and advancing and finally advancing the substrate is achieved by operation of the drive motor and substrate transport.
- 21. (Original) The method of claim 20 wherein providing a drive motor comprises providing a stepper motor and finally advancing the substrate includes operating the stepper motor in full steps.

- 22. (Original) The method of claim 21 wherein finally advancing the substrate includes operating the stepper motor in fractions of steps.
- 23. (Original) The method of claim 21 wherein finally advancing the substrate includes operating the stepper motor in microsteps.
  - 24. (Original) A backlash reduction apparatus comprising:

the backlash reduction apparatus executing a method comprising:

- a drive motor operable in increments;
- a drive train driven by the drive motor;
- at least one substrate transport mechanism connected to the drive train and driven by the drive motor therethrough;
- a controller comprising:
  - a substrate advancer in communication with the drive motor, the substrate
    advancer emitting control signals to the drive motor that cause the
    substrate to move to a point short of an intended destination; and
    a substrate final advancer in communication with the drive motor, the substrate
    final advancer sending control signals to the drive motor that cause
    the substrate to continue to the intended destination; and

advancing a substrate to a point short of a final intended position; and finally advancing the substrate to the final intended position, thereby taking up backlash in a substrate transport system.